

$$\alpha = (X X^T)^{-1} X Y^T$$

$$X_{S \times N}$$

$$Y_{1 \times N}$$

$$Y \approx \alpha^T X \quad \text{podejrzenie}$$

$$\hat{Y} = \alpha^T X = \phi(x; \alpha)$$

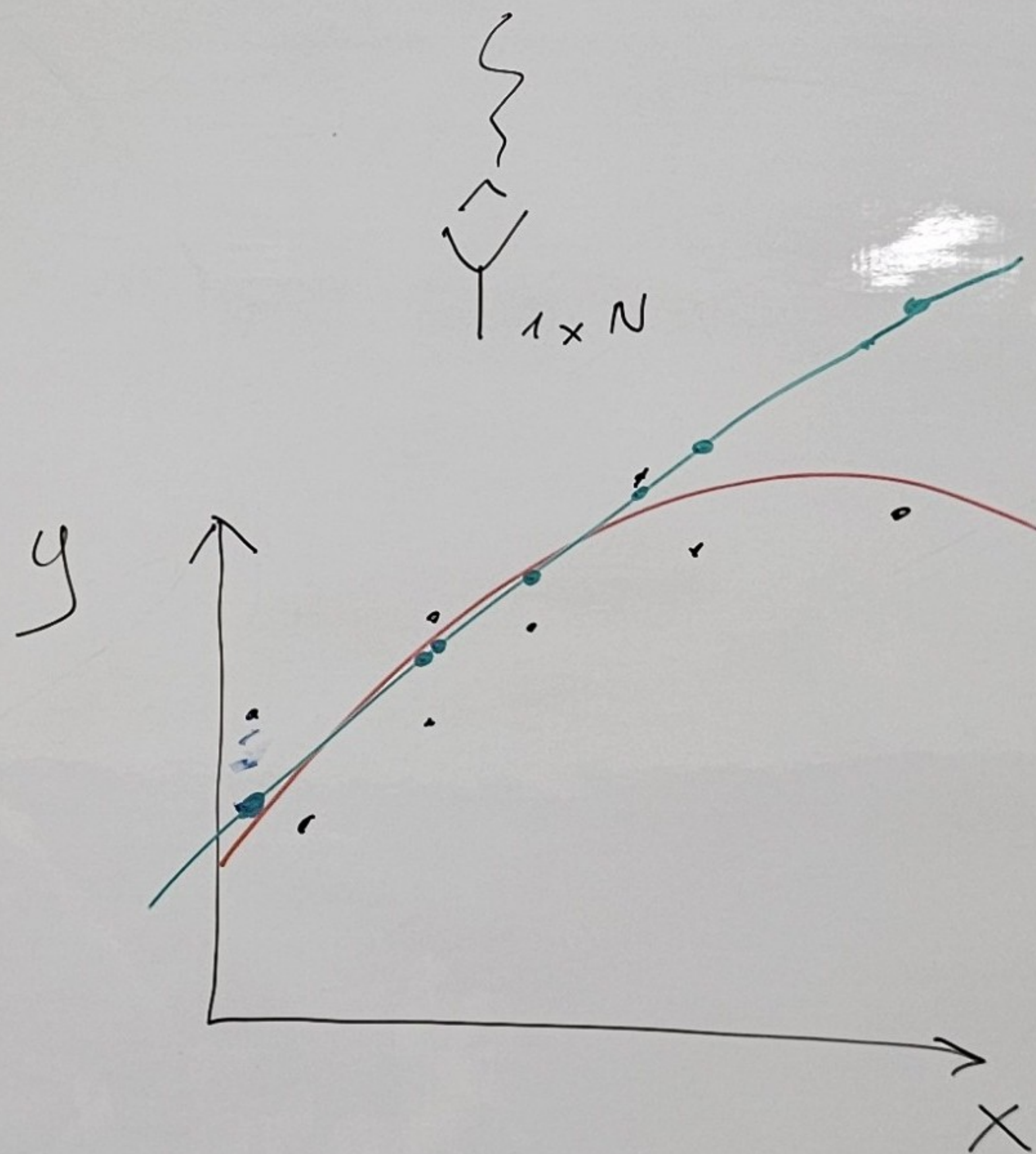
$$\hat{y} = \alpha^T x$$

$$Y = [y_1 \quad y_2 \quad \dots \quad y_N]$$

$$\hat{Y} = [\hat{y}_1 \quad \hat{y}_2 \quad \dots \quad \hat{y}_N]$$

$$E = [e_1 \quad e_2 \quad \dots \quad e_N]$$

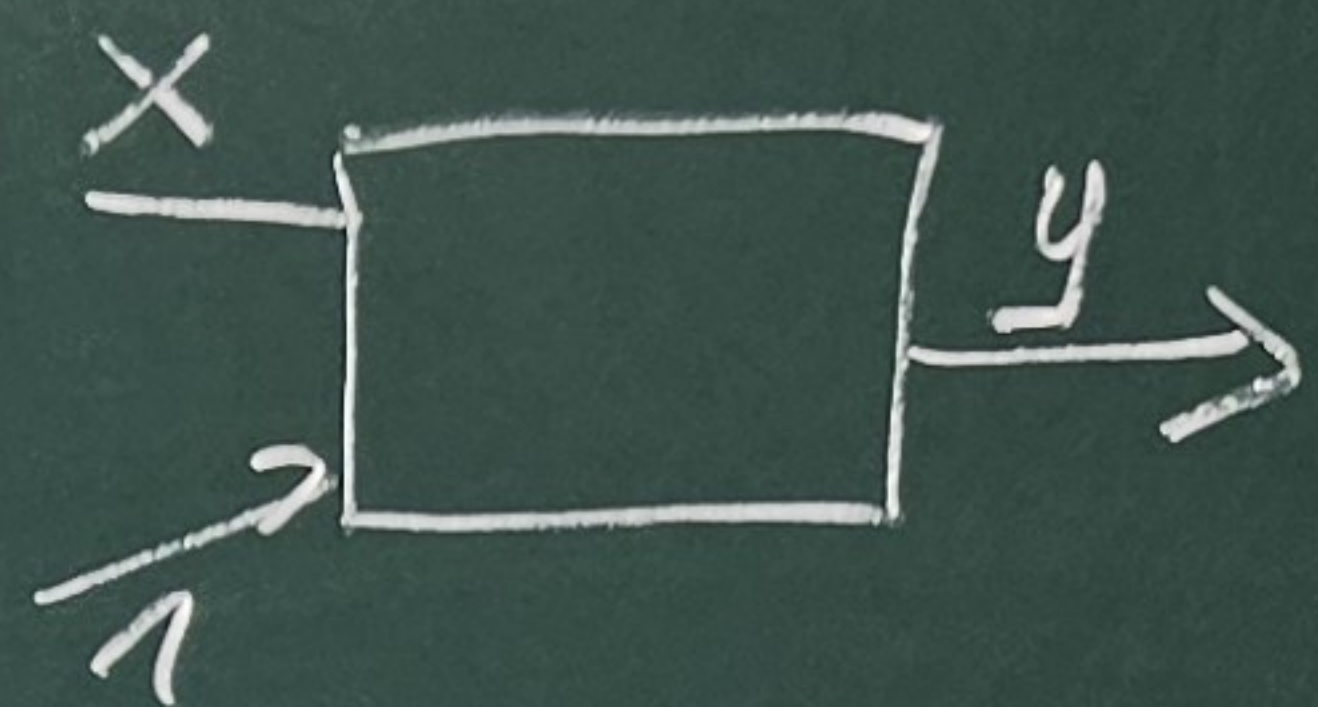
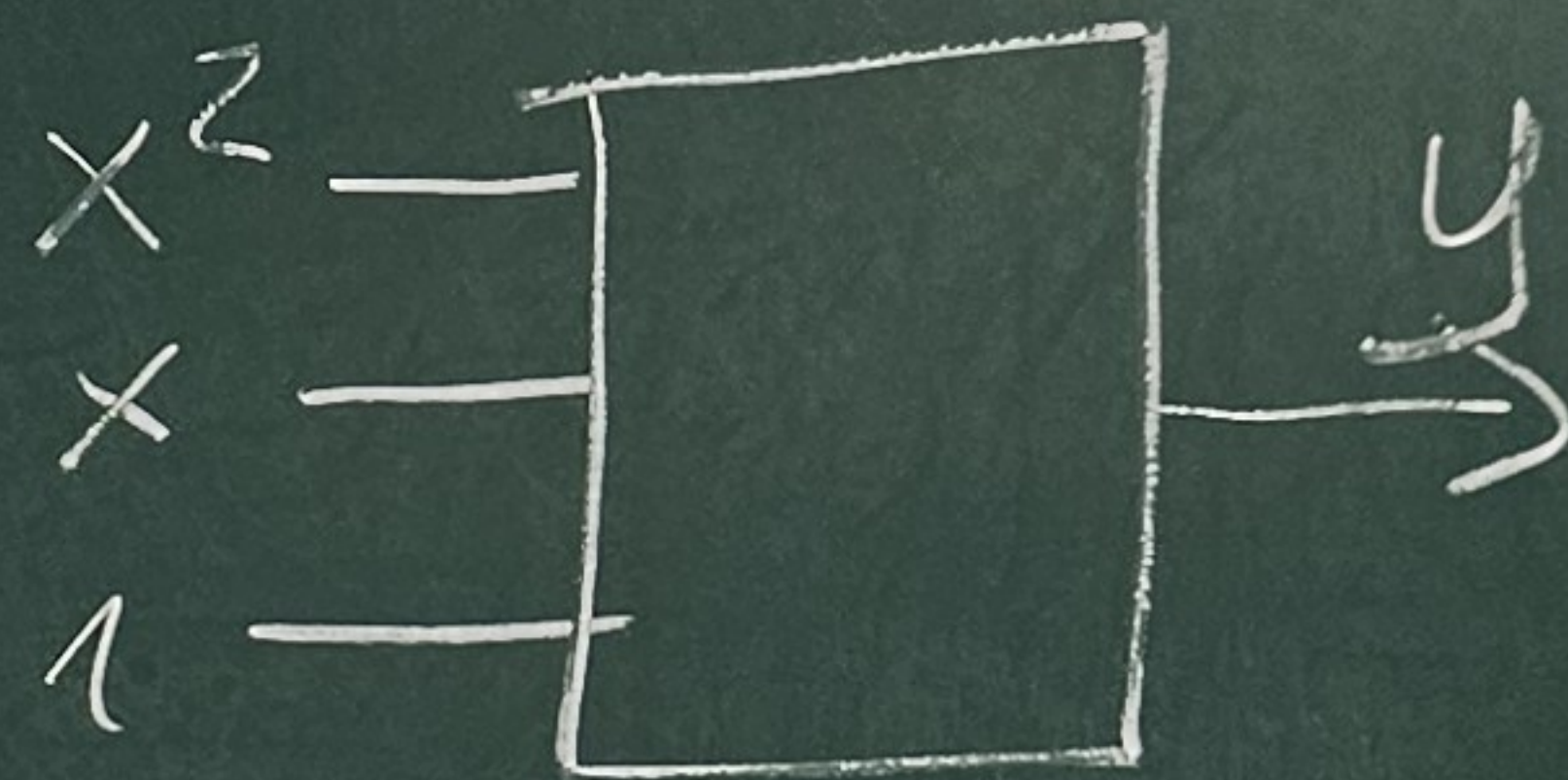
$$e_i = y_i - \hat{y}_i$$



$$\Theta = \begin{bmatrix} a \\ b \end{bmatrix}$$



$$\begin{bmatrix} x^{(1)} \\ x^{(2)} \end{bmatrix} = \begin{bmatrix} x \\ 1 \end{bmatrix}$$



$$X = \begin{bmatrix} x^{(1)} \\ 1 \end{bmatrix}$$

dla jakich x, Θ wyrażenie $\hat{y} = \Theta^T X$ opisuje zieloną linię?

$\hat{y} = ax$ nie opisuje linii zielonej

$$\hat{y} = ax + b$$

to nie jest liniowe

$7_{min} - 1 \text{ osoba}$

$8_{min} - 2 \text{ osoby}$

x	1	-1	2
y	4	0	3

$$X = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}$$

$$\bar{X} = \begin{bmatrix} 1 & 1 & 4 \\ 1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$Y = \begin{bmatrix} 4 & 0 & 3 \end{bmatrix}$$

$x^{(1)}$	1	-1	2
$x^{(2)}$	1	1	1
y	4	0	3

$$= X$$

$$\hat{y} = a_1 x^{(1)} + a_2 x^{(2)} + a_3 x^{(3)}$$

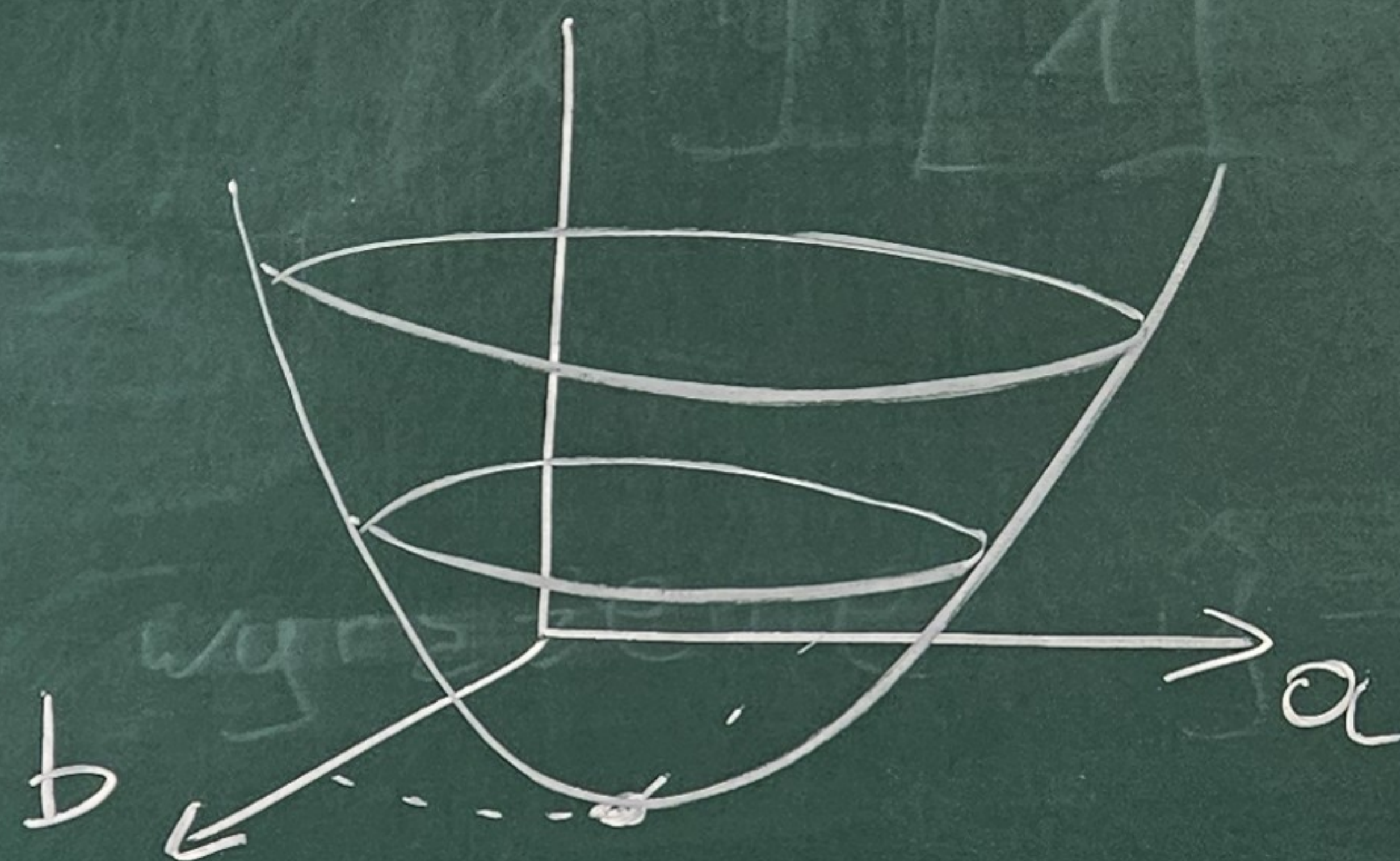
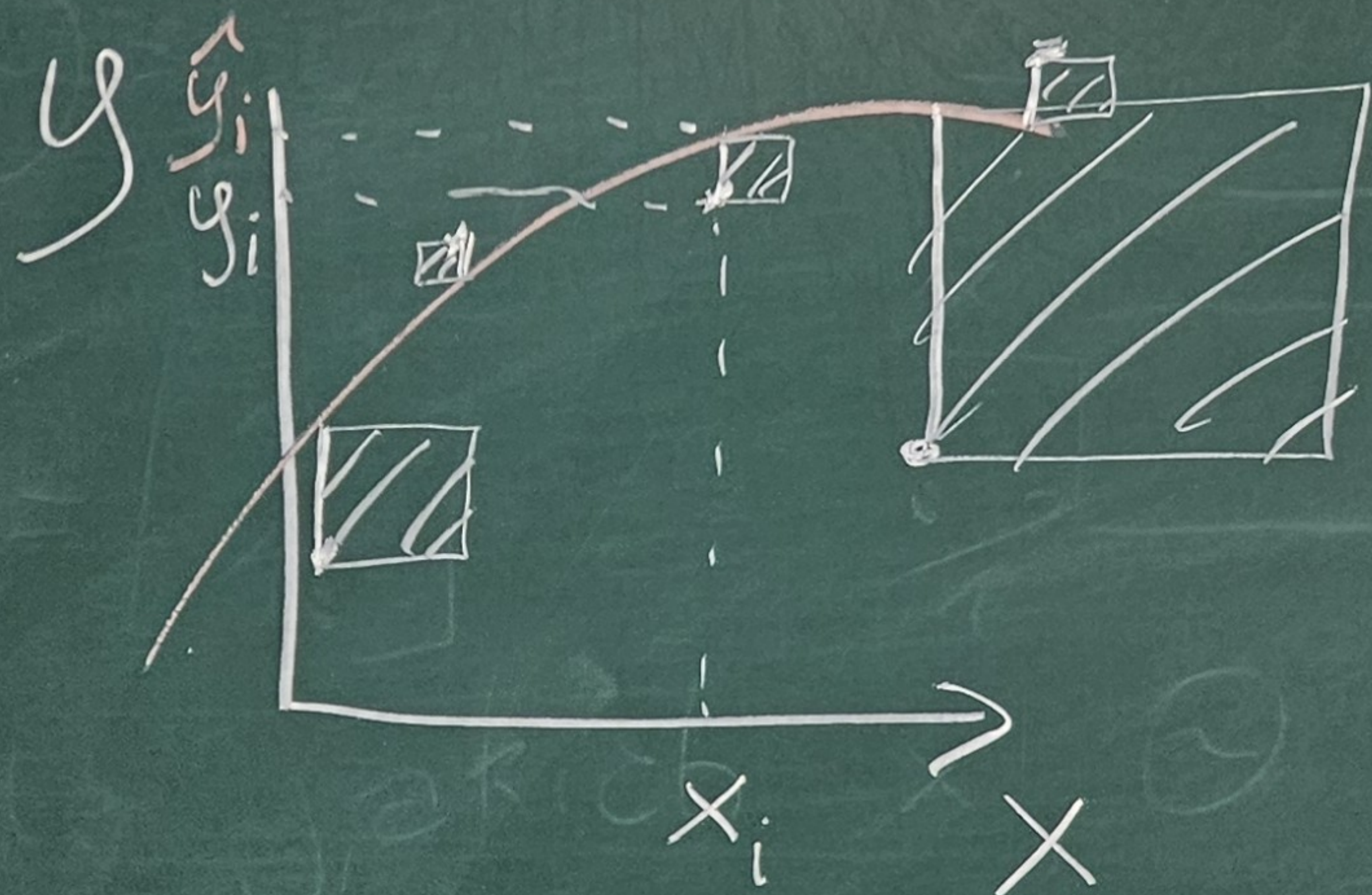
$$\hat{y} = ax^2 + bx + c$$

$$\hat{y} = \Theta^T X$$

$$\Theta = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

$$X = \begin{bmatrix} x^2 \\ x \\ 1 \end{bmatrix}$$

$$L(ax + by) = aL(x) + bL(y)$$



$$Q_1(\theta) = \frac{1}{N} \sum_{i=1}^N |e_i|$$

tylko numer

$$\frac{\partial Q}{\partial \theta} = 0$$

$$\min Q_2(\theta) = \frac{1}{N} \sum_{i=1}^N e_i^2$$

w dom

I. Model: $\hat{y} = ax$

$$\frac{\partial Q_2}{\partial a}$$

II Model: $\hat{y} = ax + b$ $\min Q_2$

$$\frac{\partial Q_2}{\partial a}$$

$$\frac{\partial Q_2}{\partial b}$$

$$Q_2 = \sum_{i=1}^N e_i^2 = E E^T = (Y - \hat{Y})(Y - \hat{Y})^T =$$

$$= (Y - \Theta^T X)(Y - \Theta^T X)^T =$$

$$= (Y - \Theta^T X)(Y^T - X^T \Theta) =$$

$$\Theta = \begin{bmatrix} \Theta_1 \\ \Theta_2 \\ \vdots \\ \Theta_5 \end{bmatrix}$$

$$Q_2 = \underbrace{Y Y^T}_I - \underbrace{Y X^T \Theta}_{II} - \underbrace{\Theta^T X Y^T}_{III} + \underbrace{\Theta^T X X^T \Theta}_{IV}$$

$$\frac{\partial Q_2}{\partial \Theta} = 0_5 - X Y^T - X Y^T + 2 X X^T \Theta = 0_5$$

$$2 X Y^T = 2 X X^T \Theta \quad \text{MNK}$$

$$\text{I} \quad \frac{\partial}{\partial \Theta} Y Y^T = 0_S$$

$$\text{II} \quad \frac{\partial}{\partial \Theta} Y X^T \Theta = (Y X^T)^T = X Y^T$$

$1 \times N \quad N \times S$

$$S \left\{ \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right\}$$

$$\text{III} \quad \frac{\partial}{\partial \Theta} \Theta^T X Y^T = X Y^T$$

$$\text{IV} \quad \frac{\partial}{\partial \Theta} \underbrace{\Theta^T X X^T \Theta}_{\substack{\text{sym} \\ 1 \times S \quad S \times N \quad N \times S \quad S \times 1}} = 2 X X^T \Theta$$

$(A + A^T) \Theta$



co to jest $\frac{1}{N} X X^T = \begin{bmatrix} \text{cov}(x^{(1)}, x^{(1)}) & \text{cov}(x^{(1)}, x^{(2)}) & \dots \end{bmatrix}$